

**Applications: Stochastic Matrices and Markov Chains**

Suppose we have a set of  $n$  states  $X = \{X_1, \dots, X_n\}$  that a given system can be in, and a *state vector*  $\vec{v} = (v_1, \dots, v_n)$  represents the distribution of things in these states. Examples include:

- $X_1, \dots, X_n$  could literally be the 50 states, and  $\vec{v}$  could be the population vector with  $v_1$  the population of Alabama,  $v_2$  the population of Alaska, etc.
- $X_1, \dots, X_n$  could represent investment accounts and  $v_i$  could represent the number of dollars allocated to the  $i$ th account,
- $X_1, \dots, X_n$  could represent positions and momenta of a set of moving molecules, with each  $\vec{v}$  representing a particular configuration.

We can model the evolution of the system over time by finding a rule that describes how to go from the current state to the next state. The system may be *deterministic*, i.e. the next state may be determined by the current state, or it may be non-deterministic, i.e., the same current state may be followed by different states.

In the latter case, we can ask what is the *probability* of an element in state  $X_i$  transitioning to state  $X_j$ , let's call this number  $P_{ij}$ . The matrix of probabilities

$$T = \begin{bmatrix} P_{11} & P_{12} & \dots & P_{1n} \\ P_{21} & P_{22} & \dots & P_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ P_{n1} & P_{n2} & \dots & P_{nn} \end{bmatrix}$$

is called the *transition matrix* of the system. If the current state is  $\vec{v} = (v_1, \dots, v_n)$  then an element in state  $X_i$  has a  $P_{ij}$  chance of moving to state  $X_j$ , so the next state vector  $\vec{w} = (w_1, \dots, w_n)$ 's  $j$ th component gets a contribution of  $P_{ij}v_i$  from state  $X_i$ . Summing over all the states, we see that  $w_j = P_{1j}v_1 + P_{2j}v_2 + \dots + P_{nj}v_n$ , which we recognize as the dot product of the row vector  $\vec{v}$  with the  $j$ th column of the transition matrix  $T$ . Thus, if  $\vec{v}$  is the current state vector, then  $\vec{w} = \vec{v}T$  if we write  $\vec{v}, \vec{w}$  as row vectors or  $\vec{w} = T^T\vec{v}$  if we write  $\vec{v}, \vec{w}$  as column vectors.

Note also that if  $X_1, \dots, X_n$  are all of the possible states of the system, then an element of state  $X_i$  has to end up in one of these states, so  $P_{i1} + P_{i2} + \dots + P_{in}$  must equal 1. A matrix is *stochastic* if it has all nonnegative entries with every column summing to 1; every stochastic matrix is the transition matrix of a probabilistic system. In particular, if the transition probabilities are fixed, i.e. not dependent on the current state, then our system is called a *Markov chain*.

**Example:** A city has three districts,  $A, B$  and  $C$  and a stable total population of 300K samples every five years. Residents of district  $A$  tend to stay put, while residents of districts  $B$  and  $C$  tend to move more. The system has transition matrix

$$T = \begin{bmatrix} 0.8 & 0.2 & 0.3 \\ 0.1 & 0.5 & 0.3 \\ 0.1 & 0.3 & 0.4 \end{bmatrix}$$

Then if the current population distribution vector is  $\vec{v} = (200K, 40K, 60K)$ , the distribution vector for the next cycle will be

$$\begin{bmatrix} 200 & 40 & 60 \end{bmatrix} \begin{bmatrix} 0.8 & 0.2 & 0.3 \\ 0.1 & 0.5 & 0.3 \\ 0.1 & 0.3 & 0.4 \end{bmatrix} = \begin{bmatrix} 170K & 78K & 96K \end{bmatrix}.$$

After playing with these matrices a little, a question suggests itself: what kinds of population distributions are stable? Well, a stable state vector must satisfy  $\vec{v} = T^T\vec{v}$ ; that is, it must be an eigenvector of  $T^T$  with eigenvalue  $\lambda = 1$ . In fact, we have

**Theorem:** (Perron-Frobenius) Every stochastic matrix has  $\lambda = 1$  as an eigenvalue, and all other eigenvalues are less than 1 in absolute value. Moreover, if the  $P_{ij}$  are all strictly greater than zero, then there is a unique

eigenvector  $\vec{v}$  with eigenvalue  $\lambda = 1$ , i.e., there is a unique stable distribution vector. If some  $P_{ij}$ s equal zero, there may be multiple distinct stable distribution vectors.

**Example:**

$$\begin{bmatrix} 0.8 - 1 & 0.2 & 0.3 \\ 0.1 & 0.5 - 1 & 0.3 \\ 0.1 & 0.3 & 0.4 - 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

so the eigenspace is spanned by  $(1, 1, 1)$  and the stable distribution vector is  $(100K, 100K, 100K)$ .